

ELECTRO TECHNOLOGY

Electric charge

$$Q = I t$$

Q electric charge C
 I electric current A
 t time s

Resistance in conductors

$$R = \frac{\rho l}{A}$$

R resistance of conductor Ω
 A area of conductor m^2
 l length of conductor m
 ρ resistivity of material $\Omega \cdot m$

Temperature effect on resistance

$$R = R_1 [1 + \alpha_{T_1} (T_2 - T_1)]$$

R resistance at T Ω
 R_1 resistance at T_1 Ω
 α_{T_1} temperature coefficient at T_1 K^{-1}
 T_2 temperature (final) K
 T_1 temperature (initial) K

Conductance

$$G = \frac{1}{R}$$

G conductance S
 R resistance Ω

Conductivity

$$\gamma = \frac{1}{\rho}$$

γ conductivity S/m
 ρ resistance $\Omega \cdot m$

Ohm's Law

$$V = R I$$

V or E voltage V
 R resistance Ω
 I electric current A

Kirchhoff's laws

First law
(Current law)

$$\Sigma I = 0$$

$$I_1 + I_2 + \dots + I_n = 0$$

Σ	summation (sum)	
I	sum of currents	A
I_1	current	A
I_2	current	A
I_n	current	A

The current flowing away from a junction point in a circuit is equal to the current flowing into the point.

Second law
(Voltage law)

$$\Sigma E + \Sigma V = 0$$

$$V = \Delta V_1 + \Delta V_2 + \dots + \Delta V_n$$

E	electro voltage	V
V	voltage	V

The sum of the potential or voltage drops taken around the circuit must be equal to the applied potential differences.

V_1	voltage drop	V
V_2	voltage drop	V
V_n	voltage drop	V
V	total voltage	V

Circuit of resistances

Series circuits

$$R_T = R_1 + R_2 + R_3 + \dots + R_n$$

R_T	total resistance	Ω
R_1	resistance in series	Ω
R_2	resistance in series	Ω
R_3	resistance in series	Ω
R_n	resistance in series	Ω

$$R_T = nR_1$$

R_1	equal resistances	Ω
n	number of equal resistances	1

Parallel circuits

$$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots + \frac{1}{R_n}$$

R_T	resulting (total) resistance	Ω
R_1	resistance in parallel	Ω
R_2	resistance in parallel	Ω
R_3	resistance in parallel	Ω
R_n	resistance in parallel	Ω

$$R_T = \frac{R_1 \cdot R_2}{R_1 + R_2}$$

R_T total resistance of two resistances in parallel circuit Ω
 R_1 } two resistances Ω
 R_2 } in parallel circuit

$$G = G_1 + G_2 + G_3 + \dots + G_n$$

G total conductance S
 G_1 } the various parts S
 G_2 } of conductance
 G_3 }
 G_n }

Work, energy

$$W = VI t = Pt$$

W work J
 V voltage V
 I electric current A
 P effect W
 t time s

Effect

$$P = VI = RI^2 = \frac{V^2}{R}$$

P effect W
 R resistance Ω

Voltage loss in two-conductors

$$V = \frac{I^2 l \rho}{A}$$

V loss of voltage V
 I electric current A
 l length m
 ρ resistance $\Omega \cdot m$
 A area m^2

Effect loss in two-conductors

$$P = \frac{I^2 l \rho}{A}$$

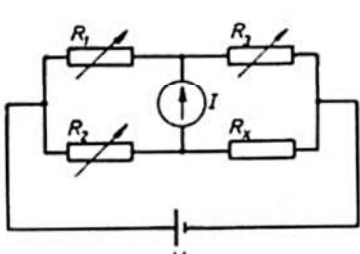
P loss of effect W

Heat generated by electric work

$$cm\Delta T = P t \eta$$

c specific heat capacity J/kgK
 m mass kg
 ΔT difference of temperature K
 P effect W
 t time s
 η efficiency 1

Electric batteries

Series circuit	$I = \frac{E}{R_i + R_y} = \frac{en_s}{rn_s + R_y}$	<p>I electric current A</p> <p>E total voltage for the complete battery V</p> <p>R_i total inner resistance Ω</p> <p>R_y external resistance Ω</p> <p>e electro voltage per unit V</p> <p>n_s number of units in series 1</p> <p>r inner resistance per unit Ω</p>
	$U = IR_y = en_s - Irr_s$	U battery voltage V
Parallel circuit	$I = \frac{E}{R_i + R_y} = \frac{e}{\frac{r}{n_p} + R_y}$	<p>I electric current A</p> <p>n_p number of units in parallel 1</p>
	$U = IR_y = e - I \frac{r}{n_p}$	U battery voltage V
Series parallel circuit	$I = \frac{E}{R_i + R_y} = \frac{en_s}{rn_s + R_y}$	I electric current A
	$U = IR_y = en_s - I \frac{rn_s}{n_p}$	U battery voltage V
Wheatstone's bridge	$\frac{R_1}{R_3} = \frac{R_2}{R_x}$	<p>R_1 } controllable resistances Ω</p> <p>R_2 }</p> <p>R_3 }</p> <p>R_x unknown resistance Ω</p> <p>$I = 0$</p>
		
Capacitors(condensers)		
Capacitance of a capacitor	$C = \frac{Q}{V} = \epsilon \frac{A}{l}$	<p>C capacitance F</p> <p>Q electric charge C</p> <p>V voltage V</p> <p>ϵ permitivity F/m</p> <p>A area m^2</p> <p>l distance m</p>

	$\epsilon = \epsilon_0 \epsilon_r$	ϵ_0 permittivity of void space	F/m
		ϵ_r relative permittivity	1
Capacitors in series circuit	$\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots + \frac{1}{C_n}$	C total capacitance	
		C_1 } capacitance of the various capacitors	F
		C_2 }	
		C_3 }	
		C_n }	
Capacitors in parallel circuit	$C = C_1 + C_2 + C_3 + \dots + C_n$	C total capacitance	F
Time constant	$\tau = RC$	τ time constant	s
		R resistance	Ω
		C capacitance	F

ELECTROMAGNETISM

Magnetic flux	$\phi = BA$	ϕ magnetic flux	Wb
		B magnetic flux density	T
		A area	m^2
Magnetic flux density	$B = \mu \frac{IN}{l}$	μ permeability	H/m
		IN magnetic force (ampere winding number)	A
		l length of a conductor	m
	$\mu = \mu_0 \mu_r$	μ_0 void space permeability	H/m
		μ_r relative permeability	1
	$B = \mu H$	H strength of magnetic field	A/m
Strength of magnetic field	$H = \frac{IN}{l}$	H strength of magnetic field	A/m

Ohm's law on magnetism

$$\phi = \frac{IN}{R_m}$$

ϕ magnetic flux Wb
 IN magnetic force A
 R_m magnetic resistance (reluctance) H^{-1}

Reluctance

$$R_m = \frac{l}{\mu A}$$

R_m reluctance H^{-1}
 l length of conductor m
 μ absolute permeability H/m
 A area m^2

Force on a current-carrying conductor in a magnetic field

$$F = BIl$$

F force N
 B magnetic flux density T
 I electric current A
 l length of conductor m

Faraday's law on inductance

$$E = -N \frac{\Delta\phi}{\Delta t}$$

E electric voltage V
 $\Delta\phi$ flux variation Wb
 Δt time variation s
 N number of windings/turns 1

$$E = -L \frac{\Delta i}{\Delta t}$$

Δi current variation A
 L self induction H

Self induction

$$L = \frac{\Delta\phi}{\Delta i} N$$

L self induction H

Self induction in a coil without iron

$$L = \frac{\mu_0 N^2 A}{l}$$

μ_0 permeability H/m
 N number of windings/turns/loops 1
 A area in section m^2
 l length of coil m

ALTERNATING CURRENT (AC)

Periodic functions

$$f = \frac{1}{T}$$

f frequency Hz
 T time for one period s

$$\omega = \frac{2\pi}{T} = 2\pi f$$

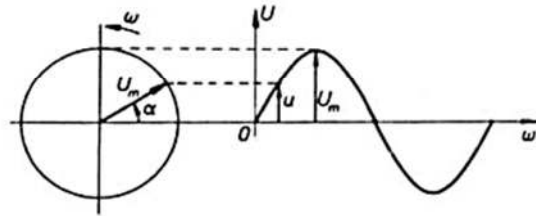
ω velocity of angel rad/s

$$\alpha = \omega t = 2\pi f t$$

α angle rad
 ω velocity of angel rad/s
 t time s

Momentary value of voltage

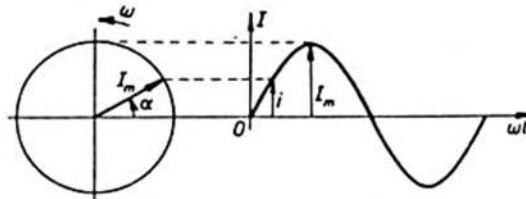
$$v = V_m \sin \alpha$$



v momentary value of voltage V
 V_m maximum value of voltage V
 α angle rad

Momentary value of current

$$I = I_m \sin \alpha$$



I momentary value of current A
 I_m maximum value of voltage A
 α angle rad

Mean value of voltage

$$V_{midl} = \frac{2}{\pi} V_m \approx 0,637 V_m$$

V_{midl} mean value of voltage V
 V_m maximum value of voltage V

Mean value of current

$$I_{midl} = \frac{2}{\pi} I_m \approx 0,637 I_m$$

I_{midl} mean value of current A
 I_m maximum value of current A

Effective value of voltage

$$V = \frac{V_m}{\sqrt{2}} \approx 0,707 V_m$$

V effective value of voltage V
 V_m maximum value of voltage V

Effective value of current $I = \frac{I_m}{\sqrt{2}} \approx 0,707 I_m$

I effective value of current A
 I_m maximum value of current A

Inductive reactance $X_L = \omega L = 2\pi fL$

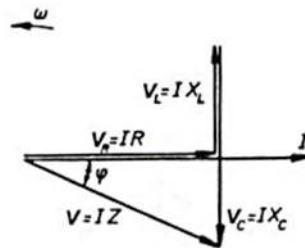
X_L inductive reactance Ω
 ω angle velocity s^{-1}
 L self induction H
 f frequency Hz

Capacitance reactance $X_C = \frac{1}{\omega C} = \frac{1}{2\pi fC}$

X_C capacitance reactance Ω

Resistance, inductive, and capacitance reactance in series

Voltage $V = \sqrt{V_R^2 + (V_L - V_C)^2}$



V total voltage V
 V_R voltage on resistance V
 V_L inductive drop of voltage V
 V_C capacitive drop of voltage V

Shifting of phase $\text{tg } \varphi = \frac{X_L - X_C}{R} = \frac{X}{R}$

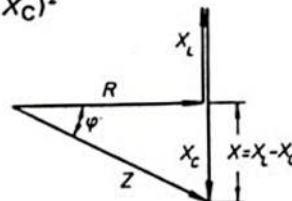
φ angel of phase rad
 X_L inductive reactance Ω
 X_C capacitance reactance Ω
 R resistance Ω
 X resulting reactance Ω
 Z circuit impedance Ω

$$\sin \varphi = \frac{X}{Z}$$

$$\cos \varphi = \frac{R}{Z}$$

Impedance

$Z = \sqrt{R^2 + (X_L - X_C)^2}$



Z circuit impedance Ω

Electric current

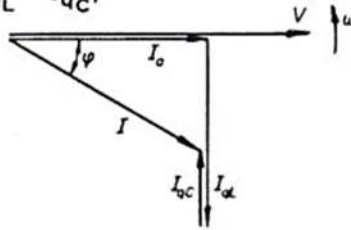
$$I = \frac{V}{Z}$$

I electric current A
 V voltage V

Parallel circuits

Electric current

$$I = \sqrt{I_a^2 + (I_{qL} - I_{qC})^2}$$



I	resulting (total) current	A
I_a	current in resistance	A
I_{qL}	current in inductive reactance	A
I_{qC}	current in capacitive reactance	A

Impedance

$$\frac{1}{Z} = \sqrt{\left(\frac{1}{R}\right)^2 + \left(\frac{1}{X_L} - \frac{1}{X_C}\right)^2}$$

Z	circuit impedance	Ω
R	resistance	Ω
X_L	inductive reactance	Ω
X_C	capacitive reactance	Ω

Admittance

$$Y = \sqrt{G^2 + B^2}$$

Y	admittance	S
B	susceptance	S
G	conductance	S

$$Y = \frac{1}{Z}$$

$$B = \frac{1}{X}$$

$$G = \frac{1}{R}$$

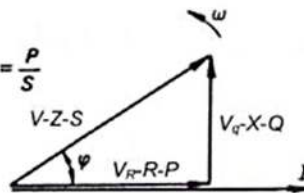
Voltage

$$V = IZ$$

V	voltage	V
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Effect factor in series circuit

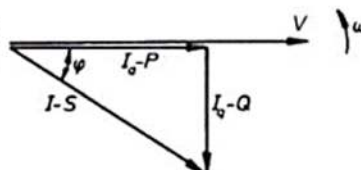
$$\cos \varphi = \frac{V_R}{V} = \frac{R}{Z} = \frac{P}{S}$$



$\cos \varphi$	effect factor	1
V_R	voltage over resistance	V
V	resulting (total) voltage	V
P	active effect	W
S	apparent effect	S

Effect factor in parallel circuit

$$\cos \varphi = \frac{I_a}{I} = \frac{P}{S}$$

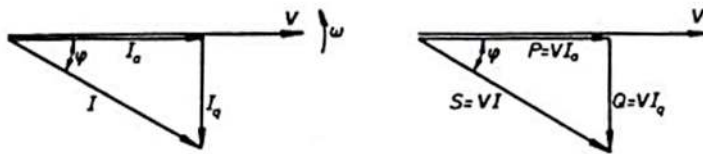


$\cos \varphi$	effect factor	1
I_a	current in resistance	A
I	resulting (total) current	A

Effect in circuits of alternating current

Active effect

$$P = VI \cos \varphi = I^2 R$$



P	active effect	W
V	voltage	V
I	electric current	A
$\cos \varphi$	effect factor	1
R	resistance	Ω

Reactive effect

$$Q = VI \sin \varphi = I^2 X$$

Q	reactive effect	VAR
X	reactance	Ω

Apparent effect

$$S = VI$$

S	apparent effect	VA
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Turnover of energy

$$W = Pt = VI \cos \varphi t$$

W	energy	J
P	active effect	W
t	time	s

Three-phase system

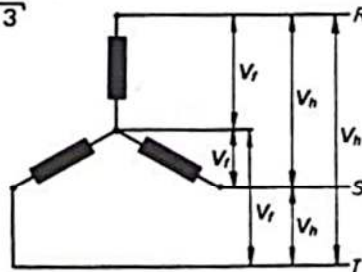
Star connection

Voltage

$$V_h = V_f \sqrt{3}$$

Electric current

$$I_h = I_f$$



V_h	main voltage	V
V_f	phase voltage	V
I_h	main current	A
I_f	phase current	A

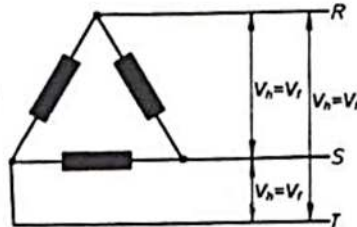
Triangular connection

Voltage

$$V_h = V_f$$

Electric current

$$I_h = I_f \sqrt{3}$$



V_h	main voltage	V
V_f	phase voltage	V
I_h	main current	A
I_f	phase current	A

Turnover of effect in the three-phase system

Active effect $P = \sqrt{3} V I \sin \varphi$

P	active effect	W
V	voltage	V
I	electric current	A
$\cos \varphi$	effect factor	1

Reactive effect $Q = \sqrt{3} V I \cos \varphi$

Q	reactive effect	VAR
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Apparent effect $S = \sqrt{3} V I$

S	apparent effect	VA
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Turnover of energy in the three-phase system
 $W = Pt = \sqrt{3} VI \cos \varphi t$

W	energy	J
P	active effect	W
t	time	s
V	voltage	V
I	electric current	A
$\cos \varphi$	effect factor	1

Transformers

Turnover one-phase transformer $\frac{I_2}{I_1} \approx \frac{V_1}{V_2} \approx \frac{N_1}{N_2}$

I_1	primary current	A
I_2	secondary current	A
V_1	primary voltage	V
V_2	secondary voltage	V

Turnover three-phase transformer $\frac{V_1}{V_2}$

N_1	number of turns on the primary part	1
N_2	number of turns on the secondary part	1
V_{1f}	primary phase voltage	V
V_{2f}	secondary phase voltage	V

Turnover of phase three-phase transformer $\frac{V_{1f}}{V_{2f}} \approx \frac{N_1}{N_2}$

Electric oscillation circuit

Frequency $f = \frac{1}{T} = \frac{1}{2\pi\sqrt{LC}}$

f	frequency	Hz
T	oscillation time	s
L	self inductance	H
C	capacitance	F

One-phase alternative current conductors

Voltage loss $V = \frac{2Il\rho \cos \alpha}{A}$

V	loss of voltage	V
I	electric current	A
l	length	m
ρ	resistivity	$\Omega \cdot m$
$\cos \varphi$	effect factor	1
A	area in section	m^2

Loss of effect $\rho = \frac{2lI^2\rho}{A}$ P loss of effect W

Three-phase alternative current conductors

Voltage loss $V = \frac{\sqrt{3}Il\rho\cos\varphi}{A}$ V loss of voltage V
 I electric current A
 l length m
 ρ resistivity $\Omega \cdot m$
 $\cos\varphi$ effect factor 1
 A area in section m^2

Loss of effect $\rho = \frac{3I^2\rho L}{A}$ P loss of effect W

ELECTRIC MOTORS

Induced voltages in DC motors $E = k_i \phi n$ E induced voltage V
 k_i motor constant 1
 ϕ magnetic flux Wb
 n rotation frequency s^{-1}

Turning moment of DC motors $T = k_d \phi I_a$ T turning moment (torsion moment) Nm
 k_d motor constant 1
 I_a rotor current A

Turning moment of AC and DC motors $T = \frac{P}{\omega} = \frac{P}{2\pi n_s}$ T turning moment (torsion moment) Nm
 P effect W
 ω angel velocity rad/s
 n_s a synchronic velocity s^{-1}

Induced voltage in AC motors $E = k_i \phi f$ E induced voltage V
 k_i motor constant 1
 f frequency Hz

Relationship between frequencies of rotation and electricity

$$n = \frac{f}{p}$$

n frequency of rotation s^{-1}
 f electric frequency Hz
 p pair of poles 1

Synchronous motor

$$n_s = \frac{f}{p}$$

n_s frequency of synchronous rotation s^{-1}

A synchronous motor

Lagging/slowng

$$s = \frac{n_s - n}{n_s}$$

s lagging/slowng (slip) 1
 n_s frequency of synchronous rotation s^{-1}
 n rotation frequency of motor s^{-1}

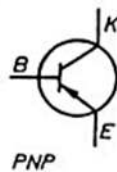
$$f_r = sf$$

f_r rotor frequency Hz
 f stator frequency Hz

Transistor

Emitter current

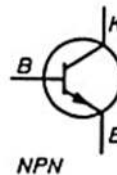
$$I_E = I_B + I_K$$



I_E emitter current A
 I_B base current A
 I_K collector current A

Amplifying factor

$$F = \frac{\Delta I_K}{\Delta I_B}$$



F amplifying factor for current with joint emitter 1